

CPC COOPERATIVE PATENT CLASSIFICATION

B PERFORMING OPERATIONS; TRANSPORTING (NOTES omitted)

TRANSPORTING

B60 VEHICLES IN GENERAL (NOTE omitted)

B60L PROPULSION OF ELECTRICALLY-PROPELLED VEHICLES (arrangements or mounting of electrical propulsion units or of plural diverse prime-movers for mutual or common propulsion in vehicles [B60K 1/00](#), [B60K 6/20](#); arrangements or mounting of electrical gearing in vehicles [B60K 17/12](#), [B60K 17/14](#); preventing wheel slip by reducing power in rail vehicles [B61C 15/08](#); dynamo-electric machines [H02K](#); control or regulation of electric motors [H02P](#)); **SUPPLYING ELECTRIC POWER FOR AUXILIARY EQUIPMENT OF ELECTRICALLY-PROPELLED VEHICLES** (electric coupling devices combined with mechanical couplings of vehicles [B60D 1/64](#); electric heating for vehicles [B60H 1/00](#)); **ELECTRODYNAMIC BRAKE SYSTEMS FOR VEHICLES IN GENERAL** (control or regulation of electric motors [H02P](#)); **MAGNETIC SUSPENSION OR LEVITATION FOR VEHICLES; MONITORING OPERATING VARIABLES OF ELECTRICALLY-PROPELLED VEHICLES; ELECTRIC SAFETY DEVICES FOR ELECTRICALLY-PROPELLED VEHICLES**

NOTES

1. This subclass, subject to the above references, covers:
 - feeding of power to auxiliary circuits;
 - current collectors; arrangements thereof on rail or road vehicles or on vehicles in general
 - electrodynamic brake systems;
 - electric propulsion of vehicles; control and regulation therefor
2. In this subclass it is desirable to classify any "additional information" which is of interest for search.

WARNING

In this subclass non-limiting references (in the sense of paragraph 39 of the Guide to the IPC) may still be displayed in the scheme.

1/00	Supplying electric power to auxiliary equipment of vehicles (circuit arrangements for charging batteries H02J 7/00)	3/00	Electric devices on electrically-propelled vehicles for safety purposes; Monitoring operating variables, e.g. speed, deceleration or energy consumption (methods or circuit arrangements for monitoring or controlling batteries or fuel cells B60L 58/00)
1/003	• {to auxiliary motors, e.g. for pumps, compressors}		
1/006	• {to power outlets}		
1/02	• to electric heating circuits		
1/04	• . . fed by the power supply line	3/0007	• {Measures or means for preventing or attenuating collisions}
1/06	• . . . using only one supply	3/0015	• . {Prevention of collisions}
1/08	• . . . Methods and devices for control or regulation	3/0023	• {Detecting, eliminating, remedying or compensating for drive train abnormalities, e.g. failures within the drive train}
1/10	• . . . with provision for using different supplies	3/003	• . {relating to inverters}
1/12	• . . . Methods and devices for control or regulation	3/0038	• . {relating to sensors}
1/14	• to electric lighting circuits	3/0046	• . {relating to electric energy storage systems, e.g. batteries or capacitors}
1/16	• . fed by the power supply line	3/0053	• . {relating to fuel cells}
1/20	• {Energy regeneration from auxiliary equipment}	3/0061	• . {relating to electrical machines}
		3/0069	• . {relating to the isolation, e.g. ground fault or leak current}
		3/0076	• . {relating to braking}

- 3/0084 . . {relating to control modules}
- 3/0092 . {with use of redundant elements for safety purposes}
- 3/02 . Dead-man's devices
- 3/04 . Cutting off the power supply under fault conditions (protective devices and circuit arrangements in general [H01H](#); [H02H](#))
- 3/06 . Limiting the traction current under mechanical overload conditions
- 3/08 . Means for preventing excessive speed of the vehicle
- 3/10 . Indicating wheel slip {; [Correction of wheel slip](#)}
- 3/102 . . {of individual wheels}
- 3/104 . . {by indirect measurement of vehicle speed}
- 3/106 . . {for maintaining or recovering the adhesion of the drive wheels}
- 3/108 . . . {whilst braking, i.e. ABS}
- 3/12 . Recording operating variables {; [Monitoring of operating variables](#)}
- 5/00 Current collectors for power supply lines of electrically-propelled vehicles (current collectors in general [H01R 41/00](#))**
- 5/005 . {without mechanical contact between the collector and the power supply line}
- 5/02 . with ice-removing device
- 5/04 . using rollers or sliding shoes in contact with trolley wire ([B60L 5/40](#) takes precedence)
- 5/045 . . {with trolley wire finders}
- 5/06 . . Structure of the rollers or their carrying means
- 5/08 . . Structure of the sliding shoes or their carrying means
- 5/085 . . . {with carbon contact members}
- 5/10 . . Devices preventing the collector from jumping off
- 5/12 . . Structural features of poles or their bases
- 5/14 . . . Devices for automatic lowering of a jumped-off collector
- 5/16 . . . Devices for lifting and resetting the collector ([B60L 5/34](#) takes precedence)
- 5/18 . using bow-type collectors in contact with trolley wire
- 5/19 . . using arrangements for effecting collector movement transverse to the direction of vehicle motion
- 5/20 . . Details of contact bow
- 5/205 . . . {with carbon contact members}
- 5/22 . . Supporting means for the contact bow
- 5/24 . . . Pantographs
- 5/26 . . . Half pantographs, e.g. using counter rocking beams
- 5/28 . . . Devices for lifting and resetting the collector
- 5/30 using springs
- 5/32 using fluid pressure
- 5/34 . with devices to enable one vehicle to pass another one using the same power supply line
- 5/36 . with means for collecting current simultaneously from more than one conductor, e.g. from more than one phase
- 5/38 . for collecting current from conductor rails ([B60L 5/40](#) takes precedence)
- 5/39 . . from third rail
- 5/40 . for collecting current from lines in slotted conduits
- 5/42 . for collecting current from individual contact pieces connected to the power supply line
- 7/00 Electrodynamic brake systems for vehicles in general**
- 7/003 . {Dynamic electric braking by short circuiting the motor}
- 7/006 . {Dynamic electric braking by reversing current, i.e. plugging}
- 7/02 . Dynamic electric resistor braking ([B60L 7/22](#) takes precedence)
- 7/04 . . for vehicles propelled by dc motors
- 7/06 . . for vehicles propelled by ac motors
- 7/08 . . Controlling the braking effect ([B60L 7/04](#), [B60L 7/06](#) take precedence)
- 7/10 . Dynamic electric regenerative braking ([B60L 7/22](#) takes precedence)
- 7/12 . . for vehicles propelled by dc motors
- 7/14 . . for vehicles propelled by ac motors
- 7/16 . . for vehicles comprising converters between the power source and the motor
- 7/18 . . Controlling the braking effect ([B60L 7/12](#), [B60L 7/14](#), [B60L 7/16](#) take precedence)
- 7/20 . Braking by supplying regenerated power to the prime mover of vehicles comprising engine-driven generators
- 7/22 . Dynamic electric resistor braking, combined with dynamic electric regenerative braking
- 7/24 . with additional mechanical or electromagnetic braking
- 7/26 . . Controlling the braking effect
- 7/28 . Eddy-current braking
- 8/00 Electric propulsion with power supply from forces of nature, e.g. sun or wind**
- 8/003 . {Converting light into electric energy, e.g. by using photo-voltaic systems}
- 8/006 . {Converting flow of air into electric energy, e.g. by using wind turbines}
- 9/00 Electric propulsion with power supply external to the vehicle (electric propulsion for monorail vehicles, suspension vehicles or rack railways [B60L 13/00](#); in combination with batteries or fuel cells within the vehicle [B60L 50/53](#))**
- 9/005 . {Interference suppression}
- 9/02 . using dc motors
- 9/04 . . fed from dc supply lines
- 9/06 . . . with conversion by metadyne
- 9/08 . . fed from ac supply lines
- 9/10 . . . with rotary converters
- 9/12 . . . with static converters
- 9/14 . . fed from different kinds of power-supply lines
- 9/16 . using ac induction motors
- 9/18 . . fed from dc supply lines
- 9/20 . . . single-phase motors
- 9/22 . . . polyphase motors
- 9/24 . . fed from ac supply lines
- 9/26 . . . single-phase motors
- 9/28 . . . polyphase motors
- 9/30 . . fed from different kinds of power-supply lines
- 9/32 . using ac brush displacement motors

13/00	Electric propulsion for monorail vehicles, suspension vehicles or rack railways; Magnetic suspension or levitation for vehicles ({tracks for Maglev-type trains E01B 25/30;} electromagnets per se H01F 7/06; linear motors per se H02K 41/00)	15/24	<ul style="list-style-type: none"> with main controller driven by a servomotor (B60L 15/28 takes precedence)
13/003	<ul style="list-style-type: none"> {Crossings; Points} 	15/26	<ul style="list-style-type: none"> with main controller driven through a ratchet mechanism (B60L 15/28 takes precedence)
13/006	<ul style="list-style-type: none"> {Electric propulsion adapted for monorail vehicles, suspension vehicles or rack railways (B60L 13/03 takes precedence)} 	15/28	<ul style="list-style-type: none"> without contact making and breaking, e.g. using a transductor
13/03	<ul style="list-style-type: none"> Electric propulsion by linear motors 	15/30	<ul style="list-style-type: none"> with means to change over to human control
13/035	<ul style="list-style-type: none"> {Suspension of the vehicle-borne motorparts} 	15/32	Control or regulation of multiple-unit electrically-propelled vehicles
13/04	<ul style="list-style-type: none"> Magnetic suspension or levitation for vehicles 	15/34	<ul style="list-style-type: none"> with human control of a setting device
13/06	<ul style="list-style-type: none"> Means to sense or control vehicle position or attitude with respect to railway 	15/36	<ul style="list-style-type: none"> with automatic control superimposed, e.g. to prevent excessive motor current
13/08	<ul style="list-style-type: none"> for the lateral position 	15/38	<ul style="list-style-type: none"> with automatic control
13/10	<ul style="list-style-type: none"> Combination of electric propulsion and magnetic suspension or levitation 	15/40	Adaptation of control equipment on vehicle for remote actuation from a stationary place (devices along the route for controlling devices on rail vehicles B61L 3/00; central rail-traffic control systems B61L 27/00)
15/00	Methods, circuits, or devices for controlling the traction-motor speed of electrically-propelled vehicles	15/42	Adaptation of control equipment on vehicle for actuation from alternative parts of the vehicle or from alternative vehicles of the same vehicle train (B60L 15/32 takes precedence)
15/002	<ul style="list-style-type: none"> {for control of propulsion for monorail vehicles, suspension vehicles or rack railways; for control of magnetic suspension or levitation for vehicles for propulsion purposes} 	50/00	Electric propulsion with power supplied within the vehicle (with power supply from force of nature, e.g. sun or wind, B60L 8/00; for monorail vehicles, suspension vehicles or rack railways B60L 13/00)
15/005	<ul style="list-style-type: none"> {for control of propulsion for vehicles propelled by linear motors} 	50/10	<ul style="list-style-type: none"> using propulsion power supplied by engine-driven generators, e.g. generators driven by combustion engines
15/007	<ul style="list-style-type: none"> {Physical arrangements or structures of drive train converters specially adapted for the propulsion motors of electric vehicles} 	50/11	<ul style="list-style-type: none"> using DC generators and DC motors
15/02	<ul style="list-style-type: none"> characterised by the form of the current used in the control circuit 	50/12	<ul style="list-style-type: none"> using AC generators and DC motors
15/025	<ul style="list-style-type: none"> {using field orientation; Vector control; Direct Torque Control [DTC]} 	50/13	<ul style="list-style-type: none"> using AC generators and AC motors
15/04	<ul style="list-style-type: none"> using dc 	50/14	<ul style="list-style-type: none"> using DC generators and AC motors
15/06	<ul style="list-style-type: none"> using substantially sinusoidal ac 	50/15	<ul style="list-style-type: none"> with additional electric power supply (with capacitors charged by engine-driven generators B60L 50/40; with batteries charged by engine-driven generators B60L 50/61)
15/08	<ul style="list-style-type: none"> using pulses 	50/16	<ul style="list-style-type: none"> with provision for separate direct mechanical propulsion
15/10	<ul style="list-style-type: none"> for automatic control superimposed on human control to limit the acceleration of the vehicle, e.g. to prevent excessive motor current (electric devices for safety purposes B60L 3/00) 	50/20	<ul style="list-style-type: none"> using propulsion power generated by humans or animals
15/12	<ul style="list-style-type: none"> with circuits controlled by relays or contactors 	50/30	<ul style="list-style-type: none"> using propulsion power stored mechanically, e.g. in fly-wheels
15/14	<ul style="list-style-type: none"> with main controller driven by a servomotor (B60L 15/18 takes precedence) 	50/40	<ul style="list-style-type: none"> using propulsion power supplied by capacitors
15/16	<ul style="list-style-type: none"> with main controller driven through a ratchet mechanism (B60L 15/18 takes precedence) 	50/50	<ul style="list-style-type: none"> using propulsion power supplied by batteries or fuel cells
15/18	<ul style="list-style-type: none"> without contact making and breaking, e.g. using a transductor 	50/51	<ul style="list-style-type: none"> characterised by AC-motors
15/20	<ul style="list-style-type: none"> for control of the vehicle or its driving motor to achieve a desired performance, e.g. speed, torque, programmed variation of speed 	50/52	<ul style="list-style-type: none"> characterised by DC-motors
15/2009	<ul style="list-style-type: none"> {for braking} 	50/53	<ul style="list-style-type: none"> in combination with an external power supply, e.g. from overhead contact lines
15/2018	<ul style="list-style-type: none"> {for braking on a slope} 	50/60	<ul style="list-style-type: none"> using power supplied by batteries (in combination with fuel cells B60L 50/75)
15/2027	<ul style="list-style-type: none"> {whilst maintaining constant speed} 	50/61	<ul style="list-style-type: none"> by batteries charged by engine-driven generators, e.g. series hybrid electric vehicles
15/2036	<ul style="list-style-type: none"> {Electric differentials, e.g. for supporting steering vehicles} 	50/62	<ul style="list-style-type: none"> charged by low-power generators primarily intended to support the batteries, e.g. range extenders
15/2045	<ul style="list-style-type: none"> {for optimising the use of energy} 	50/64	<ul style="list-style-type: none"> Constructional details of batteries specially adapted for electric vehicles
15/2054	<ul style="list-style-type: none"> {by controlling transmissions or clutches} 		
15/2063	<ul style="list-style-type: none"> {for creeping} 		
15/2072	<ul style="list-style-type: none"> {for drive off} 		
15/2081	<ul style="list-style-type: none"> {for drive off on a slope} 		
15/209	<ul style="list-style-type: none"> {for overtaking} 		
15/22	<ul style="list-style-type: none"> with sequential operation of interdependent switches, e.g. relays, contactors, programme drum 		

NOTE

This group covers adaptation of battery structures of electric vehicles, e.g. integration into control or safety systems,

B60L

B60L 50/64
(continued)

crash-resistant casings or vibration-damping means.

WARNING

Group [B60L 50/64](#) is incomplete pending reclassification of documents from group [H01M 50/20](#).

Groups [H01M 50/20](#) and [B60L 50/64](#) should be considered in order to perform a complete search.

- 50/66 . . . {Arrangements of batteries}
- 50/70 . . using power supplied by fuel cells (in combination with batteries [B60L 50/75](#))
- 50/71 . . . Arrangement of fuel cells within vehicles specially adapted for electric vehicles
- 50/72 . . . Constructional details of fuel cells specially adapted for electric vehicles
- NOTE**
This group covers adaptation of fuel cell structures of electric vehicles, e.g. integration into control or safety systems, crash-resistant casings or vibration-damping means.
- 50/75 . . using propulsion power supplied by both fuel cells and batteries
- 50/90 . using propulsion power supplied by specific means not covered by groups [B60L 50/10](#) - [B60L 50/50](#), e.g. by direct conversion of thermal nuclear energy into electricity
- 53/00 Methods of charging batteries, specially adapted for electric vehicles; Charging stations or on-board charging equipment therefor; Exchange of energy storage elements in electric vehicles**
- 53/10 . characterised by the energy transfer between the charging station and the vehicle
- 53/11 . . {DC charging controlled by the charging station, e.g. mode 4}
- 53/12 . . Inductive energy transfer
- 53/122 . . . Circuits or methods for driving the primary coil, e.g. supplying electric power to the coil
- 53/124 . . . Detection or removal of foreign bodies
- 53/126 . . . Methods for pairing a vehicle and a charging station, e.g. establishing a one-to-one relation between a wireless power transmitter and a wireless power receiver
- 53/14 . . Conductive energy transfer
- 53/16 . . . Connectors, e.g. plugs or sockets, specially adapted for charging electric vehicles
- 53/18 . . . Cables specially adapted for charging electric vehicles
- 53/20 . characterised by converters located in the vehicle
- 53/22 . . Constructional details or arrangements of charging converters specially adapted for charging electric vehicles
- 53/24 . . Using the vehicle's propulsion converter for charging
- 53/30 . Constructional details of charging stations
- 53/302 . . Cooling of charging equipment
- 53/305 . . {Communication interfaces}
- 53/31 . . Charging columns specially adapted for electric vehicles

- 53/32 . . {by charging in short intervals along the itinerary, e.g. during short stops}
- 53/34 . . Plug-like or socket-like devices specially adapted for contactless inductive charging of electric vehicles (positioning means for charging devices using inductive energy transfer [B60L 53/38](#))
- 53/35 . . Means for automatic or assisted adjustment of the relative position of charging devices and vehicles
- 53/36 . . . by positioning the vehicle
- 53/37 . . . using optical position determination, e.g. using cameras
- 53/38 . . . specially adapted for charging by inductive energy transfer
- 53/39 with position-responsive activation of primary coils
- 53/50 . Charging stations characterised by energy-storage or power-generation means
- 53/51 . . Photovoltaic means
- 53/52 . . Wind-driven generators
- 53/53 . . Batteries
- 53/54 . . Fuel cells
- 53/55 . . Capacitors
- 53/56 . . Mechanical storage means, e.g. fly wheels
- 53/57 . . Charging stations without connection to power networks
- 53/60 . Monitoring or controlling charging stations
- 53/62 . . in response to charging parameters, e.g. current, voltage or electrical charge
- 53/63 . . in response to network capacity
- 53/64 . . Optimising energy costs, e.g. responding to electricity rates
- 53/65 . . involving identification of vehicles or their battery types
- 53/66 . . Data transfer between charging stations and vehicles
- 53/665 . . . {Methods related to measuring, billing or payment}
- 53/67 . . Controlling two or more charging stations
- 53/68 . . Off-site monitoring or control, e.g. remote control
- 53/80 . Exchanging energy storage elements, e.g. removable batteries
- 55/00 Arrangements for supplying energy stored within a vehicle to a power network, i.e. vehicle-to-grid [V2G] arrangements**
- 58/00 Methods or circuit arrangements for monitoring or controlling batteries or fuel cells, specially adapted for electric vehicles**
- NOTE**
This group covers the monitoring of the operating state of batteries or fuel cells in combination with controlling the propulsion in response to the detected variables of the state.
- 58/10 . for monitoring or controlling batteries
- 58/12 . . responding to state of charge [SoC]
- 58/13 . . . Maintaining the SoC within a determined range
- 58/14 . . . Preventing excessive discharging
- 58/15 . . . Preventing overcharging
- 58/16 . . responding to battery ageing, e.g. to the number of charging cycles or the state of health [SoH]
- 58/18 . . of two or more battery modules

58/19	. . . Switching between serial connection and parallel connection of battery modules	2220/44	. . Wheel Hub motors, i.e. integrated in the wheel hub
58/20	. . . having different nominal voltages	2220/46	. . Wheel motors, i.e. motor connected to only one wheel
58/21	. . . having the same nominal voltage	2220/50	. Structural details of electrical machines
58/22	. . . Balancing the charge of battery modules	2220/52	. . Clutch motors
58/24	. . for controlling the temperature of batteries	2220/54	. . Windings for different functions
58/25	. . . by controlling the electric load	2220/56	. . with switched windings
58/26	. . . by cooling	2220/58	. . with more than three phases
58/27	. . . by heating		
58/30	. for monitoring or controlling fuel cells	2240/00	Control parameters of input or output; Target parameters
58/31	. . for starting of fuel cells	2240/10	. Vehicle control parameters
58/32	. . for controlling the temperature of fuel cells, e.g. by controlling the electric load	2240/12	. . Speed
58/33	. . . by cooling	2240/14	. . Acceleration
58/34	. . . by heating	2240/16	. . . longitudinal
58/40	. for controlling a combination of batteries and fuel cells	2240/18	. . . lateral
		2240/20	. . . angular
2200/00	Type of vehicles	2240/22	. . Yaw angle
2200/10	. Air crafts	2240/24	. . Steering angle
2200/12	. Bikes	2240/26	. . Vehicle weight
2200/14	. Vehicles with one wheel only	2240/28	. . Door position
2200/16	. Single-axle vehicles	2240/30	. . Parking brake position
2200/18	. Buses	2240/32	. . Driving direction
2200/20	. Vehicles specially adapted for children, e.g. toy vehicles	2240/34	. . Cabin temperature
2200/22	. Microcars, e.g. golf cars	2240/36	. . Temperature of vehicle components or parts
2200/24	. Personal mobility vehicles	2240/40	. Drive Train control parameters
2200/26	. Rail vehicles	2240/42	. . related to electric machines
2200/28	. Trailers	2240/421	. . . Speed
2200/30	. Trolleys	2240/423	. . . Torque
2200/32	. Waterborne vessels	2240/425	. . . Temperature
2200/34	. Wheel chairs	2240/427	. . . Voltage
2200/36	. Vehicles designed to transport cargo, e.g. trucks	2240/429	. . . Current
2200/40	. Working vehicles	2240/44	. . related to combustion engines
2200/42	. . Fork lift trucks	2240/441	. . . Speed
2200/44	. . Industrial trucks or floor conveyors	2240/443	. . . Torque
2200/46	. Vehicles with auxiliary ad-on propulsions, e.g. add-on electric motor kits for bicycles	2240/445	. . . Temperature
		2240/46	. . related to wheels
2210/00	Converter types	2240/461	. . . Speed
2210/10	. DC to DC converters	2240/463	. . . Torque
2210/12	. . Buck converters	2240/465	. . . Slip
2210/14	. . Boost converters	2240/48	. . related to transmissions
2210/20	. AC to AC converters	2240/485	. . . Temperature
2210/22	. . without intermediate conversion to DC	2240/486	. . . Operating parameters
2210/30	. AC to DC converters	2240/50	. . related to clutches
2210/40	. DC to AC converters	2240/507	. . . Operating parameters
2210/42	. . Voltage source inverters	2240/52	. . related to converters
2210/44	. . Current source inverters	2240/525	. . . Temperature of converter or components thereof
2210/46	. . with more than three phases	2240/526	. . . Operating parameters
2220/00	Electrical machine types; Structures or applications thereof	2240/527	. . . Voltage
2220/10	. Electrical machine types	2240/529	. . . Current
2220/12	. . Induction machines	2240/54	. . related to batteries
2220/14	. . Synchronous machines	2240/545	. . . Temperature
2220/16	. . DC brushless machines	2240/547	. . . Voltage
2220/18	. . Reluctance machines	2240/549	. . . Current
2220/20	. . DC electrical machines	2240/60	. Navigation input
2220/30	. . Universal machines	2240/62	. . Vehicle position
2220/40	. Electrical machine applications	2240/622	. . . by satellite navigation
2220/42	. . with use of more than one motor	2240/625	. . . by GSM
		2240/627	. . . by WLAN
		2240/64	. . Road conditions

2240/642	. . . Slope of road	2270/147	. . . electro magnetic [EMI]
2240/645	. . . Type of road	2270/20	. Inrush current reduction, i.e. avoiding high currents when connecting the battery
2240/647	. . . Surface situation of road, e.g. type of paving	2270/30	. Preventing theft during charging
2240/66	. . Ambient conditions	2270/32	. . of electricity
2240/662	. . . Temperature	2270/34	. . of parts
2240/665	. . . Light intensity	2270/36	. . of vehicles
2240/667	. . . Precipitation	2270/38	. . of data
2240/68	. . Traffic data	2270/40	. related to technical updates when adding new parts or software
2240/70	. Interactions with external data bases, e.g. traffic centres	2270/42	. Means to improve acoustic vehicle detection by humans
2240/72	. . Charging station selection relying on external data	2270/44	. Heat storages, e.g. for cabin heating
2240/80	. Time limits	2270/46	. Heat pumps, e.g. for cabin heating
2250/00	Driver interactions		
2250/10	. by alarm		
2250/12	. by confirmation, e.g. of the input		
2250/14	. by input of vehicle departure time		
2250/16	. by display		
2250/18	. by enquiring driving style		
2250/20	. by driver identification		
2250/22	. by presence detection		
2250/24	. by lever actuation		
2250/26	. by pedal actuation		
2250/28	. . Accelerator pedal thresholds		
2250/30	. by voice		
2260/00	Operating Modes		
2260/10	. Temporary overload		
2260/12	. . of combustion engines		
2260/14	. . of transmissions		
2260/16	. . of electrical drive trains		
2260/162	. . . of electrical cells or capacitors		
2260/165	. . . of converters		
2260/167	. . . of motors or generators		
2260/20	. Drive modes; Transition between modes		
2260/22	. . Standstill, e.g. zero speed		
2260/24	. . Coasting mode		
2260/26	. . Transition between different drive modes		
2260/28	. . Four wheel or all wheel drive		
2260/30	. . Engine braking emulation		
2260/32	. . Auto pilot mode		
2260/34	. . Stabilising upright position of vehicles, e.g. of single axle vehicles		
2260/40	. Control modes		
2260/42	. . by adaptive correction		
2260/44	. . by parameter estimation		
2260/46	. . by self learning		
2260/48	. . by fuzzy logic		
2260/50	. . by future state prediction		
2260/52	. . . drive range estimation, e.g. of estimation of available travel distance		
2260/54	. . . Energy consumption estimation		
2260/56	. . . Temperature prediction, e.g. for pre-cooling		
2260/58	. . . Departure time prediction		
2270/00	Problem solutions or means not otherwise provided for		
2270/10	. Emission reduction		
2270/12	. . of exhaust		
2270/14	. . of noise		
2270/142	. . . acoustic		
2270/145	. . . Structure borne vibrations		